

Presentations from Optimize This! 2014







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Improving the Propulsive Performance of Ships

Richard Korpus

American Bureau of Shipping

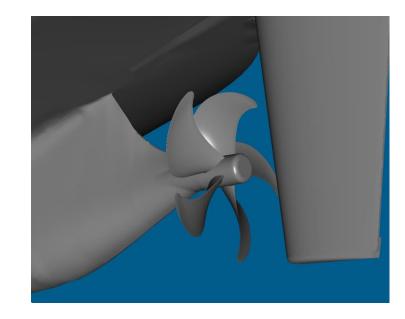
Red Cedar's "Optimize This" Conference Dearborn, Michigan, October 15, 2014

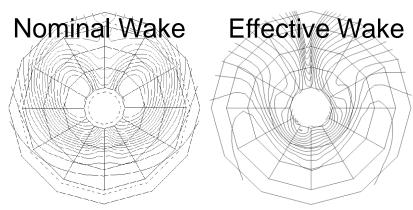
The Maritime Classification Business

- Insurance companies and international safety & environmental regulatory agencies require expensive and potentially hazardous assets like ships and offshore structures meet design and operational standards set by unbiased and technically competent third parties ("Classification Societies").
- Designs and owners must meet the rules set forth by Class, and their assets maintained to the Class standard.
- Class Societies offer various services to improve competitiveness.
 One of ABS's advantages is state-of-the-art technology to help owners and operators make difficult design decisions.
- Two of the most advanced and versatile technologies available for towards that end are Computational Fluid Dynamics (CFD) and performance improvement.

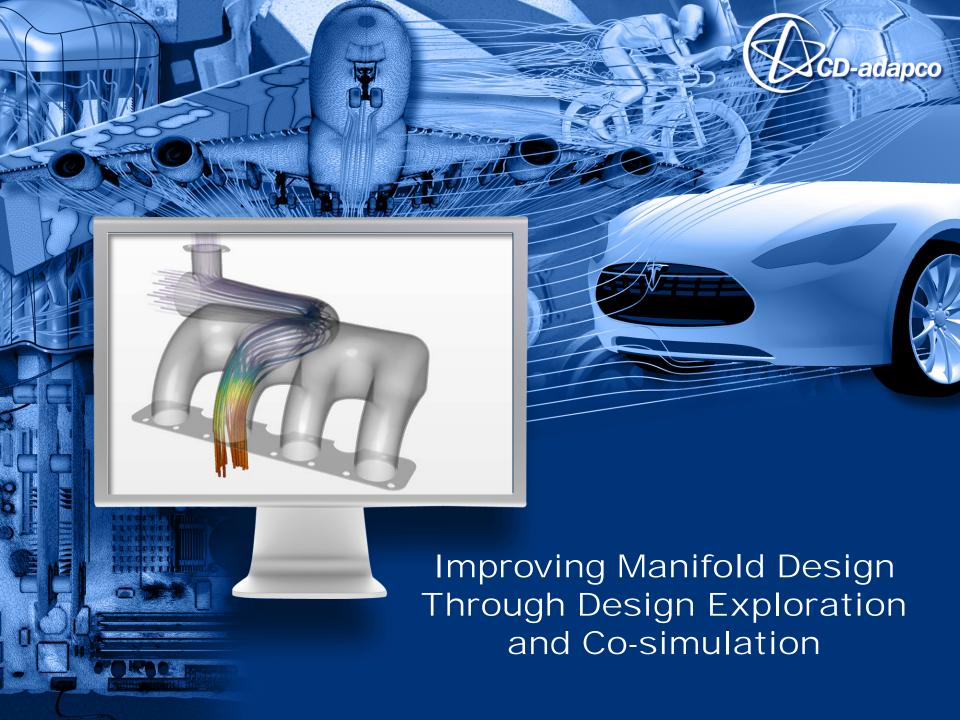
Biggest Challenge: Propeller Design

- Propellers operate in the nonuniform viscous wake of a hull.
- Optimal propellers need to be designed in their true operating environment.
- Today's state-of-the-art still assumes steady inflow with corrections for spatial and temporal averages of inflow.
- Hull wake is only available at model scale.





ABS



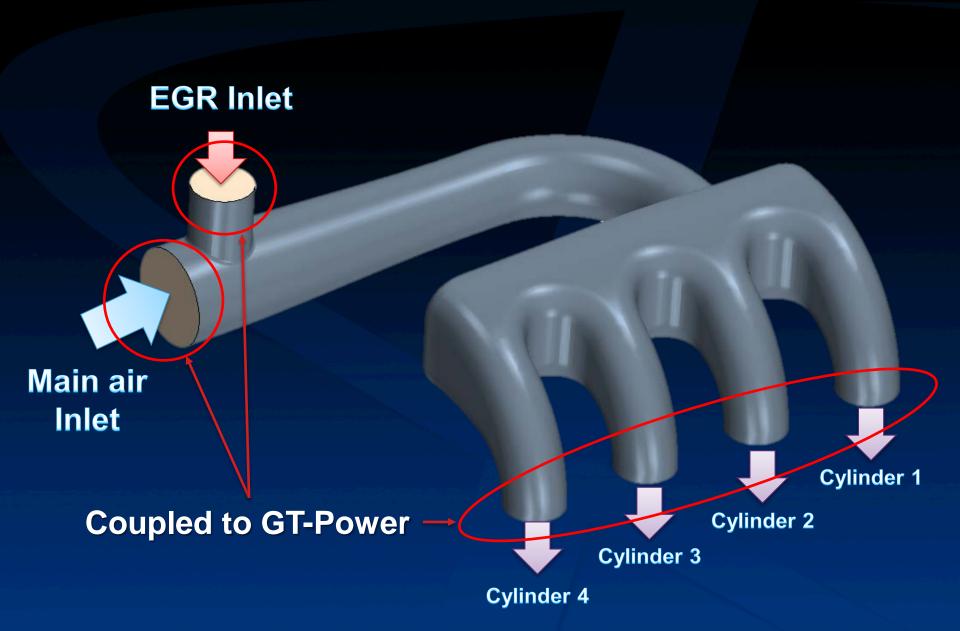
Introduction



- Two studies presented to demonstrate how HEEDS technology may be used to improve designs involving co-simulation
- Design exploration of an inlet manifold
 - GT-SUITE 1D engine performance model
 - STAR-CCM+ 3D CFD air flow model & 3D internal CAD model
 - Optimate+ for process integration & design exploration
- Design exploration of an exhaust manifold
 - NX CAD model
 - Abaqus 3D structural/thermal model
 - STAR-CCM+ 3D CFD air flow model
 - HEEDS for process integration & design exploration

Case 1 - Inlet manifold

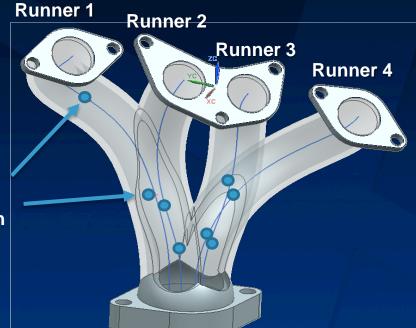




Case 2 - Exhaust manifold



- Parametric 3D geometry modelled in Siemens NX CAD
 - Each of the four runners is defined using a spline
 - The points defining the spline are varied by + or 10% of the baseline position
 - x, y, z coordinates of two interior points for four runners (24 variables in total)



Spline Points for Runner 1 (x, y, z coordinates of each spline point is a variable)

Multi-Objective Optimization of a 3R Robotic Manipulator Equipped with Nonlinear Transmission Joints

David Fredriksson, Foad Mohammadi



The aim



Investigate the possibility of using a nonlinear transmission joint in a robotic arm to decrease the power consumption of the arm while maintaining (or potentially improving) manipulability and payload performance, by exploiting the unique characteristics of the joint.

Agenda

- The nonlinear transmission joint
- The 3R manipulator
- Inverse Kinematics & Manipulability Ellipsoid Analysis
- The optimization setup
- Results
- Conclusion





Collaborative Design Optimization Process



Javier Rodríguez Director Vehicle Integration, EDAG Inc. Velayudham Ganesan Manager, CAE, EDAG Inc.

Presentation Themes



- Introduction

 Mass reduction feasibility study
- Weight Optimization
 Strategies, CAE Based Optimization
- Collaborative Optimization Process
 Sub-systems, Full Vehicle, Optimization Stages
- Strategy Analysis
 Sub-systems and Full Vehicle Strategies
- Cost Impact
 MDO Output, Optimized LWV
- **LWV Performance Assessment** *Trade-off*
- 7 References

Introduction Weight Reduction Feasibility Study



- Weight Reduction Studies initiated by EPA
- Collaborative optimization carried out for:
 - Toyota Venza, mid size cross over utility (CUV)
 - Pick-up Truck
- The studies were performed by considering the following parameters:
 - Only technologies and techniques currently feasible for manufacturability were considered
 - Options had to be cost effective for a MY 2017, 2020 high volume production vehicles respectively [1].
 - The vehicle NVH modal characteristics and crash performance had to be maintained
 - The total cost impact needed to be minimal
 - The overall vehicle safety performance had to be maintained

Introduction Weight Reduction Feasibility Study



- Weight Reduction Scope
- Body-In-White (BIW), a prime system typically comprises of 20-25% of the total curb weight
 - Uni-Body, typically cabin BIW (e.g: Sedan, CUV, ...)
 - Body-On-Frame, typically pick-up trucks
- Closures & Bumpers
 - Doors, Fenders, Hood and Tailgate
 - Front and Rear Bumpers
- The weight reduction and cost effects [5] of multiple lightweight designs were analyzed and evaluated together using advanced optimization and engineering tools
- This presentation is about the processes used for the evaluation of the body system
 - Sub-systems and Integrated Full Vehicle
- Utilizing advanced cooperative optimization computer-aided engineering (CAE) tools including HEEDS MDO

Recent Developments in Evolutionary Multi-objective Optimization

Kalyanmoy Deb

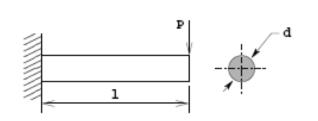
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Multi-Objective Optimization

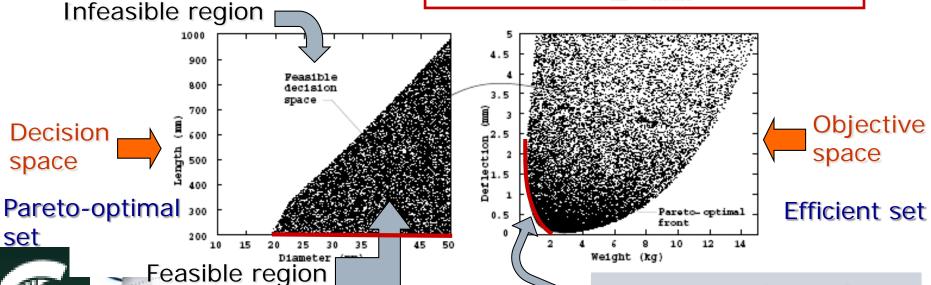


Minimize $f_1(d,l) = \rho \frac{\pi d^2}{4} l$

Minimize $f_2(d,l) = \delta = \frac{64Pl^3}{3E\pi d^4}$

subject to $\sigma_{\max} \leq S_y$

 $\delta \le \delta_{\rm max}$



"Optimize This" Presentation 15 October 2014 A number of solutions are optimal



Using HEEDS to Determine Required System Complexity Early in the Design Cycle

Jesper Slattengren
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Background

- We are all familiar with how to use HEEDS to find the optimal solution to a design project.
- But can HEEDS be used to help define the system topology early on in the design cycle?
- This presentation shows an example on how HEEDS was used to not only find a feasible solution, but also how it was used to determine that a cheaper damper could be used.

PRADE tors, objectives and constraints

- Requirement summary:
 - Find ride elements that:
 - Satisfy the constraints
 - Optimizes the ride criteria

Simulation	Constraint	#
10" half-round GVW	Vertical accel	4
10" half-round CVW	Vertical accel	4
Drop-off GVW	Ride frequencies	4
	Ride damping	4
Drop-off CVW	Ride frequencies	4
	Ride damping	4
Offroad CVW	Absorbed power	4
Offroad GVW	Absorbed power	4
Step steer	Yaw overshoot	1
	Roll overshoot	1
	Yaw damping	1
	Roll damping	1
Constant radius	Understeer gradient	2
	Max lateral accel	1
	Roll gradient	1
Total		40



Factors				
	Dual rate spring	5		
Eront	Position sensitive damper	13		
Front	Anti-roll bar	3		
	Geometry	3		
	Dual rate spring	5		
Rear	Position sensitive damper	13		
Real	Anti-roll bar	3		
	Geometry	1		
Total		46		

Objective: Minimize the sum of the ride measures

ATKINS

Safety Driven Optimization of Offshore Platform Orientation for Oil & Gas

Gerard Reynolds

October 15th, 2014

Optimize This! 2014 International HEEDS User Conference

Background Information

- Type: Tension Leg Platform (TLP)
- Size: 300 ft x 300 ft x 100 ft
- Personnel on Board: 180
- Access: 90 min by Helicopter
- Cost: \$3.5 bn
- Production: \$10 MM/day



Consequences



Piper Alpha



Deepwater Horizon



Thunderhorse



Petronas 36

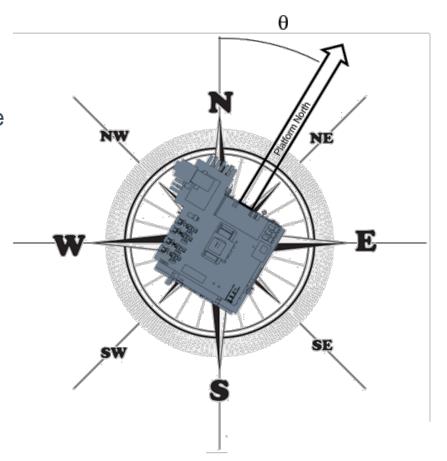
Problem Statement

Considering:

- Ventilation
- Helideck Impairment from Turbine Exhaust

Find:

Optimum Platform Orientation

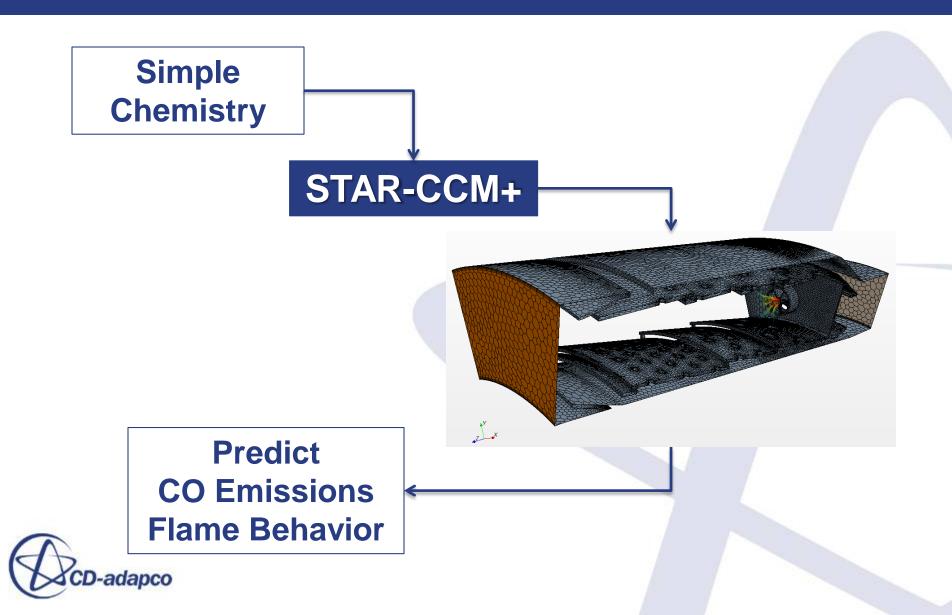


HEEDS/ DARS-Basic Global Mechanism Optimization

Megan Karalus, PhD



Why optimize a global mechanism?





Outline



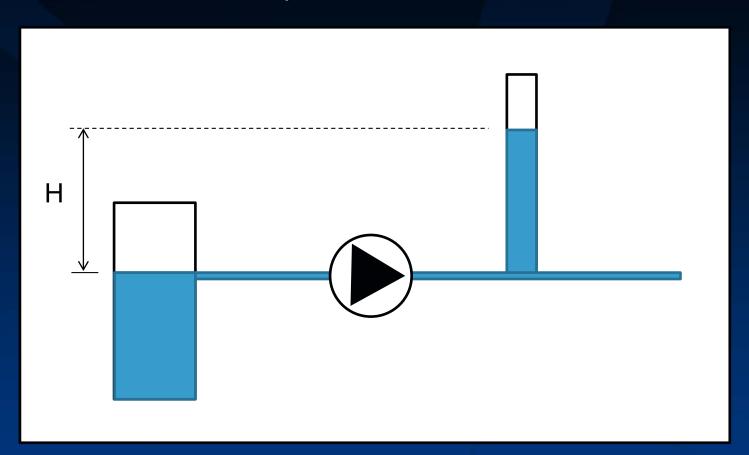
- **⊗** Background
- **Optimization objective**
- **Analysis tools**
- **⊗** Results

Background



Pumps are designed to:

- Move a certain volume of liquid
- Produce a certain exit pressure, which is measured in meters of head



Background



- **®** Reducing the power required to drive the pump:
 - Allows for a smaller motor
 - Reduces operating cost
- A small reduction in required power translates to large cost savings



Optimization Statement



Objective

- 1. Reduce the power required to drive the pump Constraints
- Retrofit the impeller only (same casing)
- **Maintain the specified volumetric flow rate**
- **Maintain the specified outlet pressure**









Car Testing

2014 - BTCC









Testing Programme

- The current generation of BTCC car has not tested at Guadix before
- Drivers Marc Hynes and Sam Tordoff had not been to Guadix before
- 2009 was Triple Eights last visit to the circuit for which we have a lot of historical data
- How did we approach these issues with simulation?



Circuito Guadix

European Race Track

- Commonly used for testing
- Located in southern Spain
- New to 888 Racing
- How to prepare both cars and drivers for testing?







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